



# Probabilistic Graphical Models & Probabilistic AI

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Lecture 5: Undirected GMs

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Reading: See course homepage



# Logistics

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- **No class 2/11**
- HW2 deadline pushed to **2/11 11:59pm**
- **Quiz in-class on 2/13**
  - Quiz format: 3 HW problems, 2 new problems

# Today

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- Undirected Graphical Models
  - Markov Random Fields
  - Restricted Boltzmann Machines
  - Conditional Random Fields

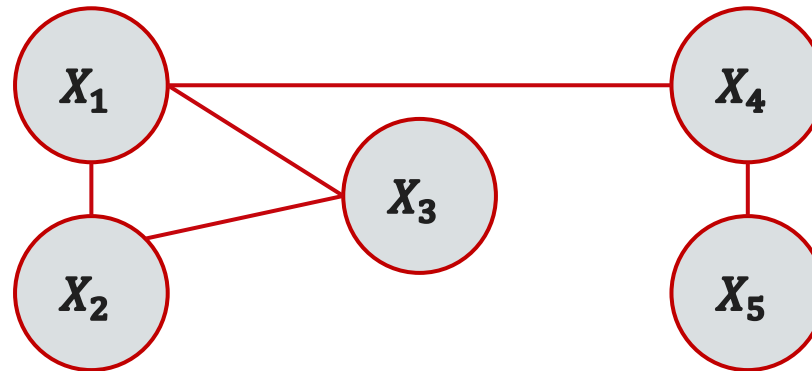




# Undirected Graphical Models

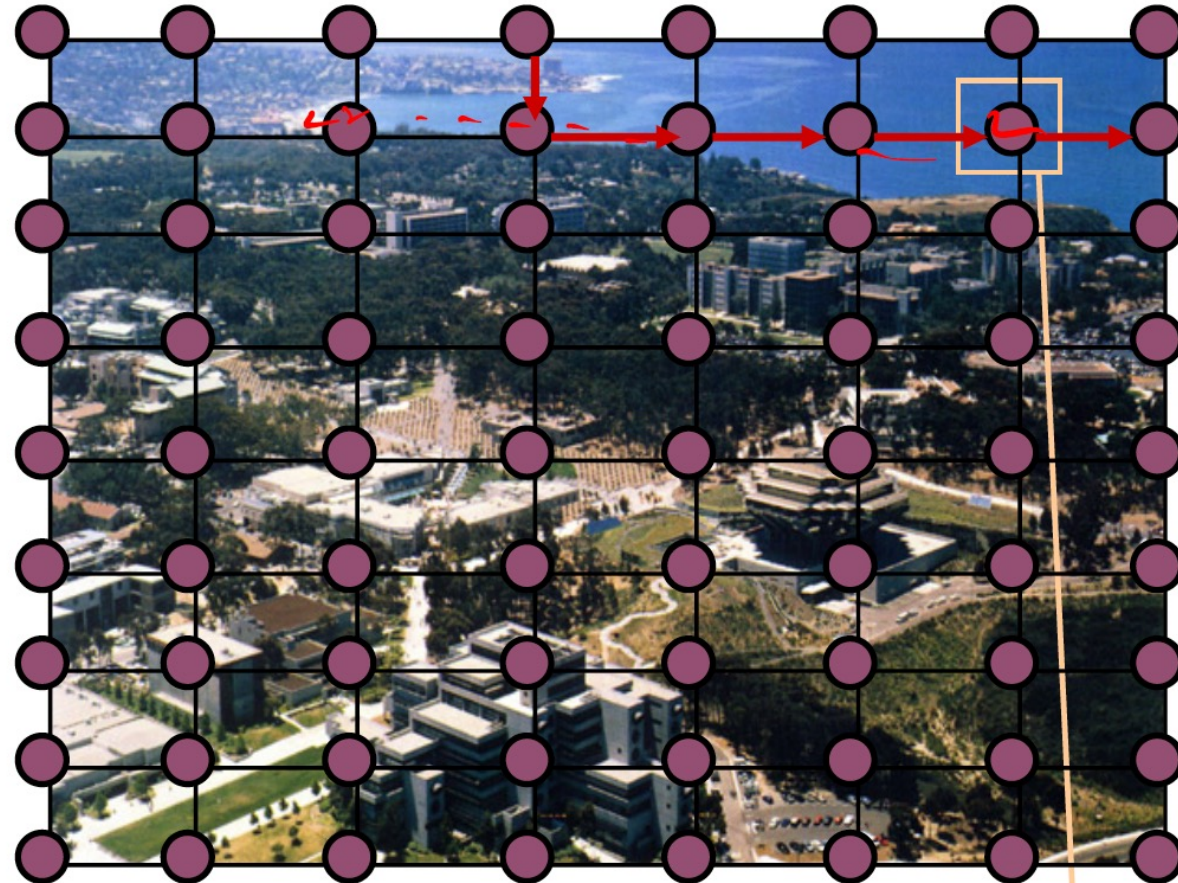
# Undirected Graphical Models

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- Pairwise relationships
- No explicit way to generate samples
- Contingency constraints on node configurations

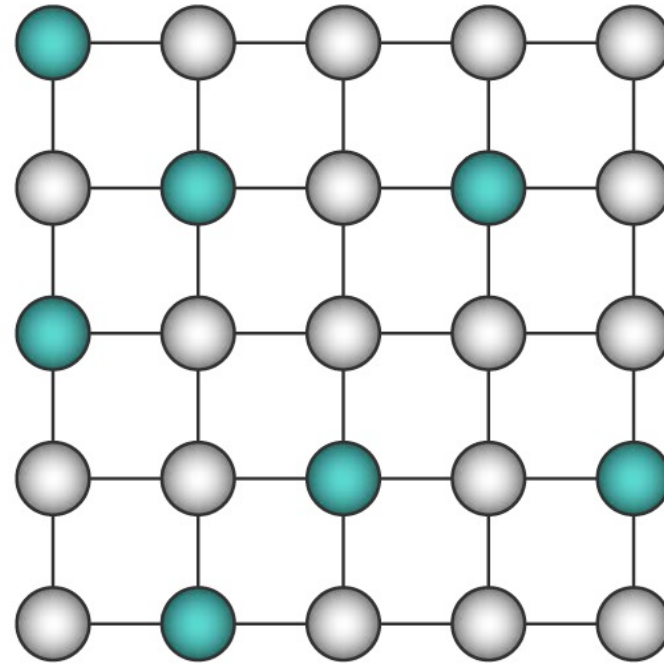
# Example: Lattice



air or water ?



# Example: Lattice



- Naturally arises in image processing, lattice physics, etc
- The states of adjacent / nearby nodes are coupled due to pattern continuity, electro-magnetic force, etc.

# Representing Undirected Graphical Models

- An ***undirected graphical model*** represents a distribution  $P(X)$  defined by an undirected graph  $H$  and a set of positive ***potential functions***  $\psi$  associated with the cliques of  $H$  such that:

$$P(X_1, \dots, X_n) = \frac{1}{Z} \prod_c \psi_c(X_c) \quad \text{“Gibbs distribution”}$$

where  $Z$  represents the **partition function**:  $Z = \sum_X \prod_c \psi_c(X_c)$ .

- The potential function can be understood as a “score” of the joint configuration

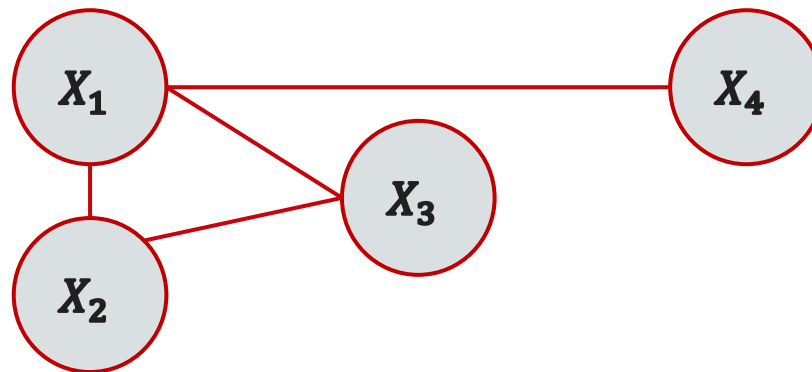
**Are  $\psi_c(X_c)$  probability densities?**

**Is  $P(X)$  a proper probability density?**



# What is a clique?

- For  $G = \{V, E\}$ , a clique (complete subgraph) is a subgraph  $G' = \{V' \subseteq V, E' \subseteq E\}$  such that nodes in  $V'$  are **fully connected**.
- A **maximal** clique is a clique such that any superset  $V'' \supset V$  is *not* a clique.

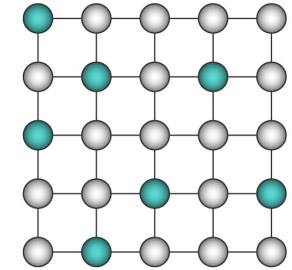


Maximal cliques:  $\{X_1, X_2, X_3\}, \{X_1, X_4\}$

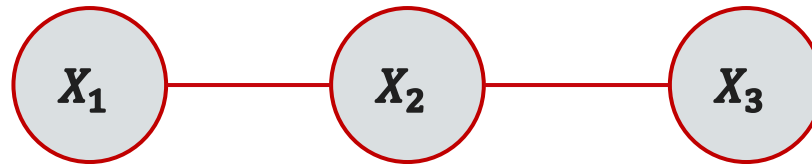
Sub-cliques:  $\{X_1, X_2\}, \{X_2, X_3\}, \{X_1, X_3\}, \{X_1\}, \{X_2\}, \{X_3\}, \{X_4\}$

# Example Lattice: Ising Model from Physics

- Used to describe ferromagnetism
- Each node  $i$  has a spin variable  $X_i \in \{-1, +1\}$
- Let potential function for an edge  $(i, j)$  be  $\psi_{ij}(X_i, X_j) = \exp(J_{ij}X_iX_j)$  (neighboring states share spins with some strength)
- $P(X) = \frac{1}{Z} \prod_c \psi_c(X_c) = \frac{1}{Z} \exp\{\sum_{i,j} \psi_{ij}(X_i, X_j)\}$

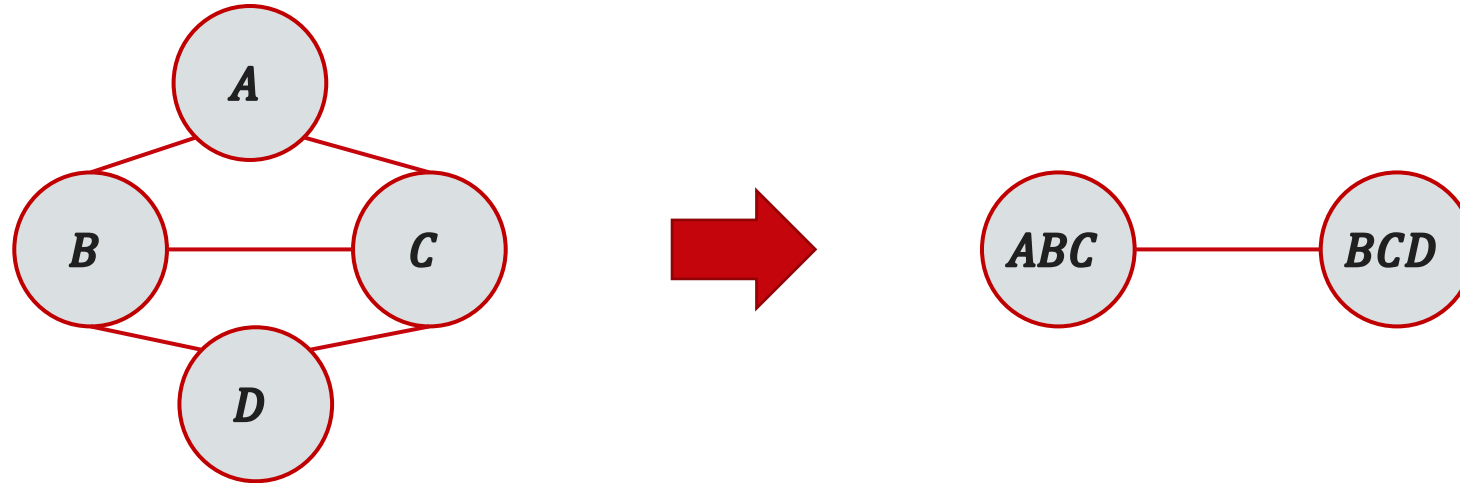


# Interpretation of Clique Potentials



- This model implies  $X_1 \perp X_3 \mid X_2$ , so joint must factorize as:  
$$P(X_1, X_2, X_3) = P(X_2)P(X_1 \mid X_2)P(X_3 \mid X_2)$$
- We could write as  $P(X_1, X_2)P(X_3 \mid X_2)$  or  $P(X_2, X_3)P(X_1 \mid X_2)$ , but:
  - Cannot have all potentials be **marginals**
  - Cannot have all potential be **conditionals**
- Clique potentials can be thought of as general “compatibility” of their variables, but not as probability distributions.

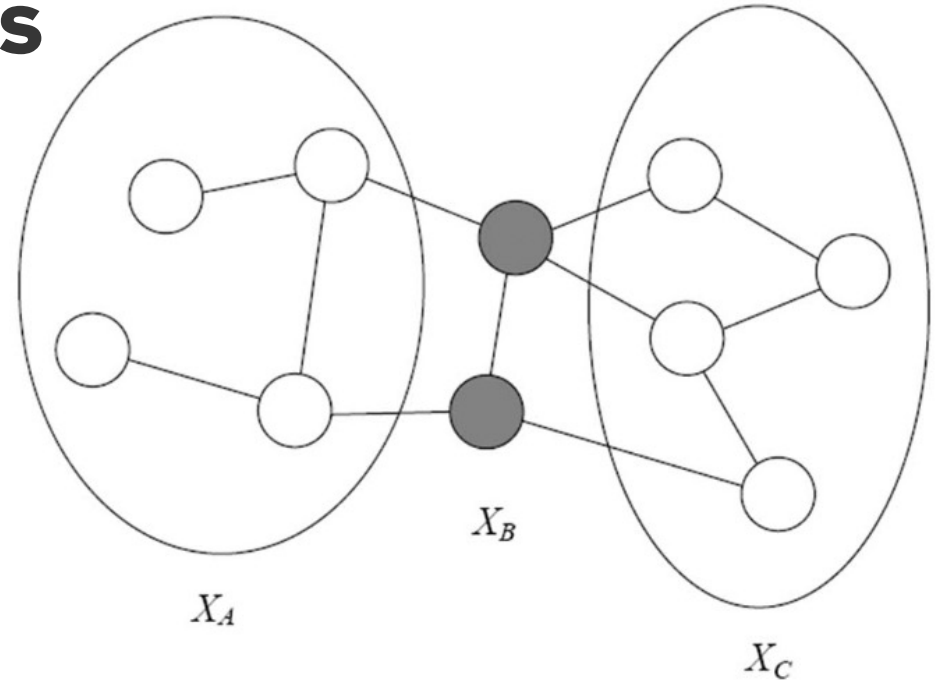
# Example UGM: Maximal Cliques



$$P(A, B, C, D) = \frac{1}{Z} \psi_{ABC}(A, B, C) \psi_{BCD}(B, C, D)$$
$$Z = \sum_{ABCD} \psi_{ABC}(A, B, C) \psi_{BCD}(B, C, D)$$

# Global Markov Independencies

- Let  $H$  be an undirected graph:



- $B$  **separates**  $A$  and  $C$  if every path from a node in  $A$  to a node in  $C$  passes through a node in  $B$ :

We write  $sep_H(A; C | B)$

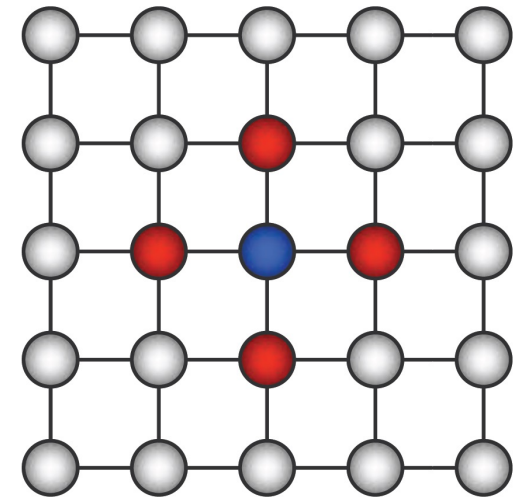
- A probability distribution satisfies the **global Markov property** if for any disjoint  $A, B, C$  such that  $B$  separates  $A$  and  $C$ ,  $A$  is independent of  $C$  given  $B$ :  $I(H) = \{A \perp C | B : sep_H(A; C | B)\}$

# Local Markov Independencies

- For each node  $X_i$  there is a unique Markov blanket of  $X_i$ , denoted  $MB_{X_i}$ , which is the set of neighbors of  $X_i$  in the graph.

- The **local Markov independencies** in  $H$  are:

$$I_l(H) = \{X_i \perp V - \{X_i\} - MB_{X_i} \mid MB_{X_i} : \forall i\}$$



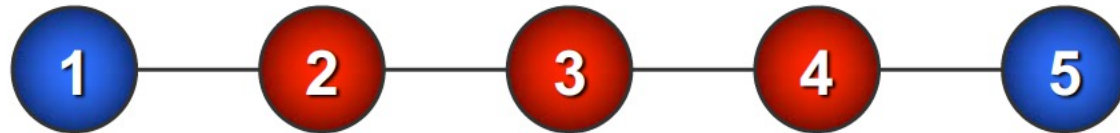
- In other words,  $X_i$  is independent of the rest of the nodes in the graph given its immediate neighbors.

# Pairwise Markov Independencies

- The pairwise Markov independencies associated with  $H$  are:

$$I_P(H) = \{X \perp Y \mid V - \{X, Y\} : \{X, Y\} \notin E\}$$

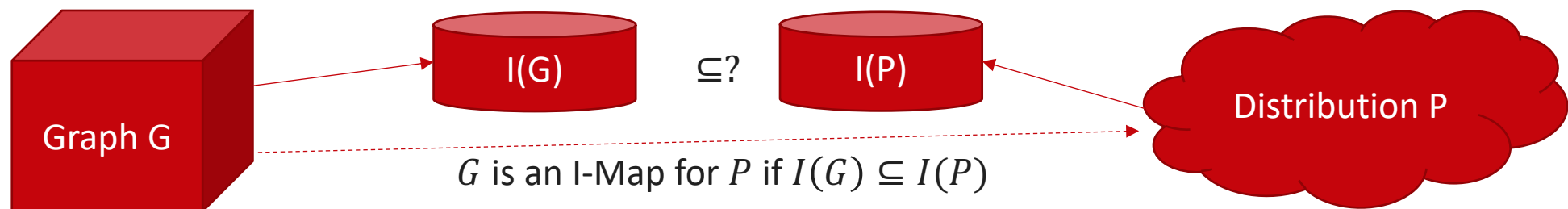
e.g.



$$X_1 \perp X_5 \mid \{X_2, X_3, X_4\}$$

# Recall: I-Maps

- Independence set: Let  $P$  be a distribution over  $X$ . We define  $I(P)$  to be the set of independences  $(X \perp Y \mid Z)$  that hold in  $P$ .
- I-Map: Let  $G$  be any graph object with an associated independence set  $I(G)$ . We say that  $G$  is an **I-map** for an independence set  $I$  if  $I(G) \subseteq I$ .
- I-Map of Distribution: We say  $G$  is an I-map for  $P$  if  $G$  is an I-map for  $I(P)$ , when we use  $I(G)$  as the associated independence set.



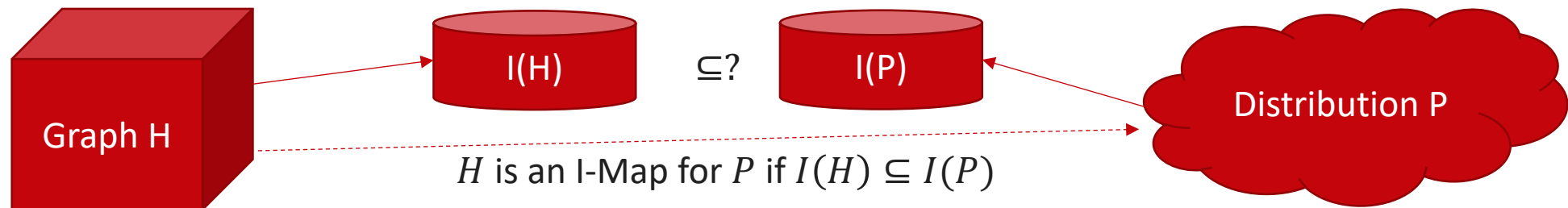


# I-Maps of UG

- An UG  $H$  is an I-Map for a distribution  $P$  if  $I(H) \subseteq I(P)$
- $P$  is a **Gibbs Distribution** over  $H$  if it can be represented as:

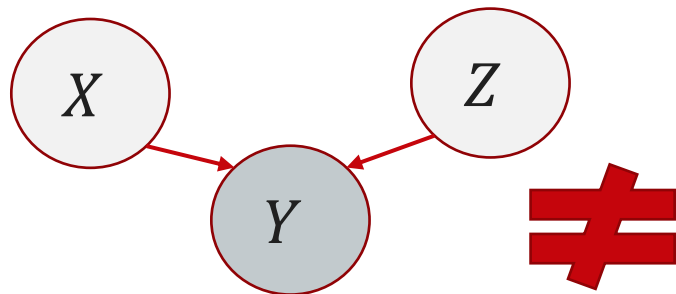
$$P(X) = \frac{1}{Z} \prod_{c \in \mathcal{C}} \psi_c(X_c)$$

- Theorem (soundness): If  $P$  is a Gibbs Distribution over  $H$ , then  $H$  is an I-Map of  $P$ .

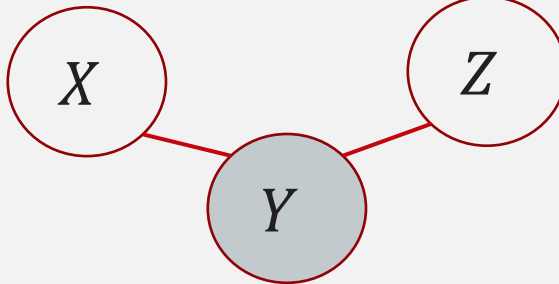


# Perfect Maps

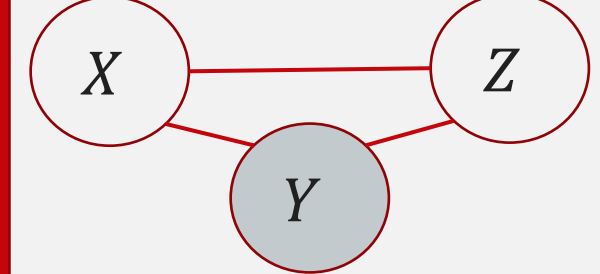
- An UG  $H$  is a **perfect map** for  $P$  if for any  $X, Y, Z$ , we have that  $sep_H(X; Z | Y) \Leftrightarrow X \perp Z | Y$
- Not every distribution has a perfect map as an UG.
  - Example: V-structure



$$I(G_{directed}) = \{X \perp Z, X \perp\!\!\!\perp Z | Y\}$$

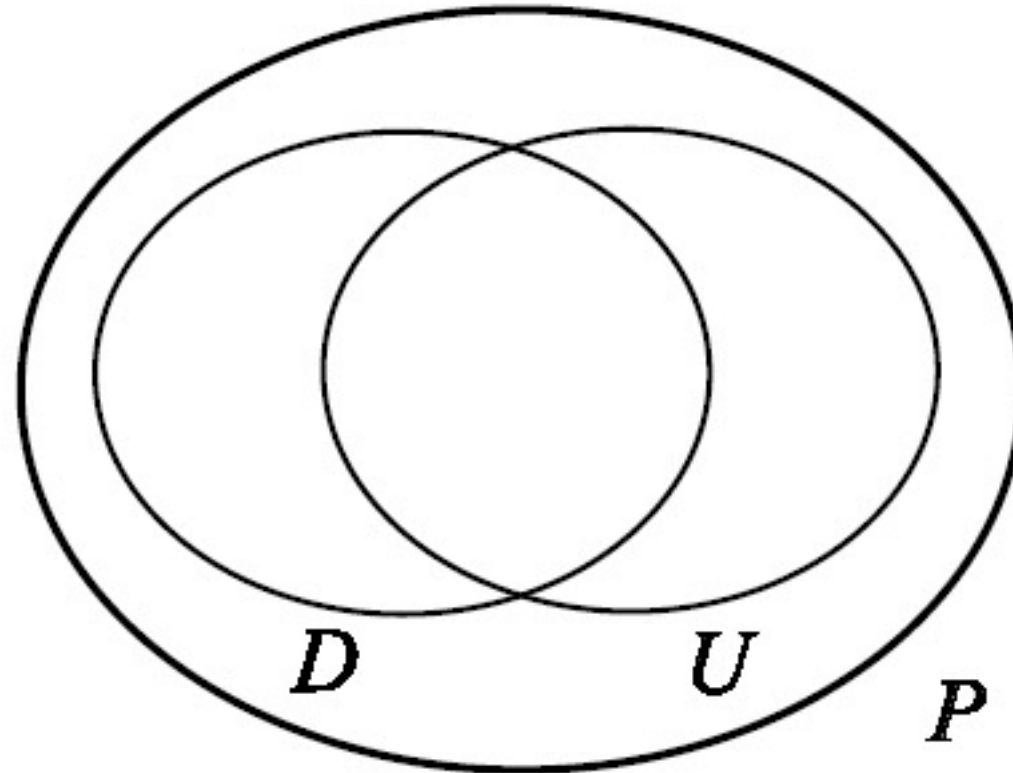


$$I(H_{undirected}) = \{X \perp Z, X \perp Z | Y\}$$



$$I(H_{undirected}) = \emptyset$$

# GMs and UGMs rep. overlapping sets of dists



# Exponential Families

- Constraining clique potentials to be positive could be inconvenient (e.g., the interactions between a pair of atoms can be either attractive or repulsive).
- We can represent a clique potential  $\psi$  in an **unconstrained** form using a real-valued “energy” function  $\phi$  and have:

$$\psi_c(X_c) = \exp(-\phi_c(X_c))$$

- This gives the joint a nice additive structure:

$$P(X) = \frac{1}{Z} \exp \left\{ - \sum_{c \in \mathcal{C}} \phi_c(X_c) \right\} = \frac{1}{Z} \exp \{ -H(X) \}$$

“Energy”

In physics, this is called the **Boltzmann distribution**.

In statistics, this is called a **log-linear model**.



# Aside: MAP Inference = Free Energy Minimization

$$P_{Boltzmann}(X) = \operatorname{argmin}_H F(P(X; H)) = \operatorname{argmin}_H E[H(X)] - TS(P(X))$$

Distribution  
observed in nature

Free energy

Expected energy

Entropy at  
temp T

Negative log likelihood

Entropy = Uncertainty - LogPrior

$$Q^*(\theta) = \operatorname{argmin}_Q F(Q) = \operatorname{argmin}_Q E_{Q(\theta)}[-\log P(X | \theta)] - TS(Q) - E_{Q(\theta)}[\log P(\theta)]$$

Will make more sense after we study variational inference

Questions?

